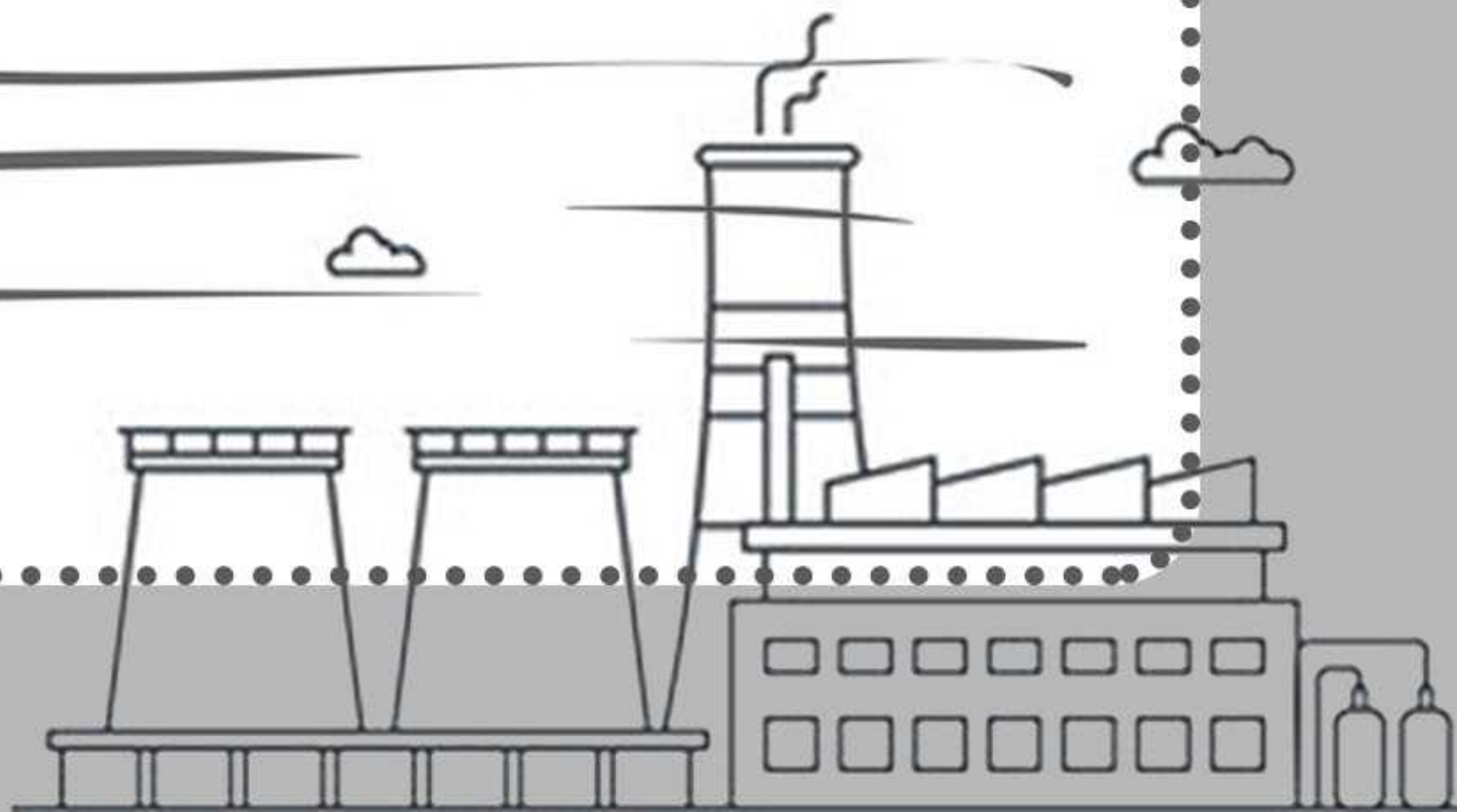


WEEKLY NOTEBOOK

Logistics

second semester
2021



* Logistics

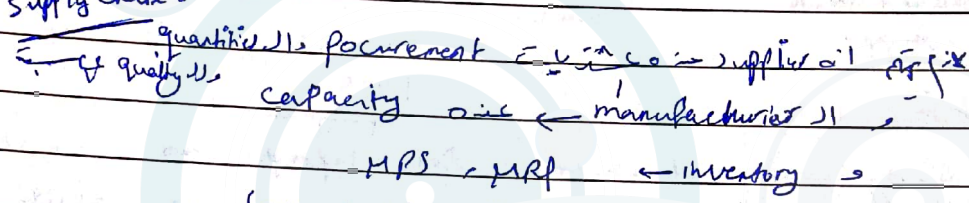
Polohn $\Rightarrow$ suppliers in supply chain.

Distribution Center $\Rightarrow$ used more than central Distributer.

- supply chain differ from supply chain management.

+ Logistics
+ Log management

supply chain:



(logistics) is transportation & Logistics

Logistics is (product service) is a big & complex supply chain.

- Amazon is a big & complex supply chain.

* Demand include D.C & Customer.

- Forward logistics towards customer.

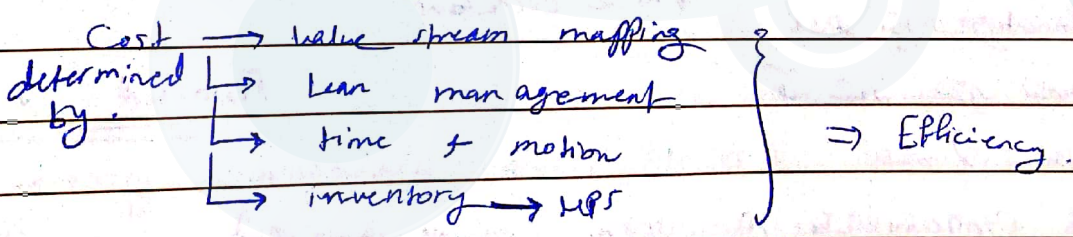
- Reverse (backward) " " opposite direction. (because of Awkward pieces)

- Sync: synchronisation (synchronization)

- ERP & supply chain $\Rightarrow$ Enterprise Resource planning.

Technology in logistics definition.

- How many times they deliver service within the range that they order? (customer satisfaction) $\Rightarrow$ Efficiency



⇒ Logistics management is a subsystem "subactivities" of supply chain management.

- types of supply chains :-

1 - pull → make to order ⇒ customer pull supply chain (MTO)

by make order ⇒
Stock

lead time short

rise-rise. for all
purch.

2 - make to assembly ⇒ restaurants, Dell laptop. ⇒ (push then pull.) MTA, MTO

3 - make to stock (MTS) ⇒ pps ⇒ inventory + safety stock. + etc.

- push supply chain → ~~inventory~~ stocks

* pull → demand can't be forecasted because it doesn't have pattern (increasing - decreasing trend + so on)

* push (make-to-stock) : Forecasting

* 3 types of flows in supply chain:

- ⇒ ① product → may be a reverse flow if it rework
- ② Information (feedback) mainly backward. requirements mainly forward.
- ③ money - flow mainly backward flow.
 - like it's in the air → forward. not air.

⇒ 3rd party logistics Example : Aramex - Agility

↳ Inventory in place
like warehouse
like courier

(logistics) is

Assorted : Goods

↳ Allows Company to do core work. → main goal of 3PL.

- Vendor $\rightarrow$ EDT $\rightarrow$ $\text{وقت التسليم من المورد}$
supply توريد $\text{الوقت الذي يستغرقه المورد لتوفير البضائع}$

- Least amount of inventory $\rightarrow$ 1. make to order
then

2. make to assembly
then

3. make to stock.

- In-transit inventory: البضائع في الطريق

- Reasons to hold inventory: $\text{أسباب الاحتفاظ بالمخزون}$

* Service level: percentage of orders to be fulfilled
right way (without waiting).
trade-off $\rightarrow$ without Backorder.

* reduce transportation cost: تقليل تكلفة النقل
 $\rightarrow$ efficiency $\rightarrow$ الكفاءة

* cope with randomness: to ensure that I have quantity
that for highest demand.
demand from customer $\vee$ lead time of supplier - lead time: it supplier
variables, supply me with orders
by diff. duration each
time

* speculate on price patterns.

* Logistics is responsible on 3 activities:

① Order processing.

② Inventory management. إدارة المخزون by check quantities to send it.

③ Freight transportation.

transmission نقل

stock piles مخزون

Inventory management إدارة المخزون سياسات

speculate: تخمين

$\rightarrow$ to make decision, When, How much, How.

(Q, R) , (T, S) , (s, S) .

* Mode choice in Freight Transportation → know minimum cost & way to transport like plane, ship, ... goods or services.

False. → marketing not in activities.

↓ just in logistics activities: Transportation, - cost ← Inventory, ~~app~~ order processing.

Cost → Distance, time, cost.

* difference the strategic, tactical and operation levels is time. (Cultures & equipment)

Strategic → ~~operational~~ ^{operational} → in facilities planning

- Resource Allocation: ^{الموارد} Resources

Facilities

Tactical Level.

- Capacity Allocation: ^{القدرة} Capacity

Facilities

الموارد

Strategy & tactical requirements

- Supply chain Activities:

ppc, Facilities, Logistics, Business

* Costs in logistics system: 4 essential types

1. Transportation costs (المواصلات)

2. Handling costs (معالجة)

3. Holding costs (opportunity cost) (cost of capital)

4. Facility rent cost. ^{المكان} ~~المكان~~ → Facility ^{المكان} ~~المكان~~ → Inventory ^{المكان} ~~المكان~~

- Normalizing costs: consider cost per time period / per Area (transportation)

* Comparing costs of carriers or modes (المواصلات) → ^{المواصلات} ~~المواصلات~~

↓ ultimate objective of logistics: minimize total cost when selecting mode of transportation.

⇒ often requires trading off inventory + transportation costs.

To like balancing these costs to know how much to stock in inventory.

* Inventory costs: 2 types.
 ① Holding cost (cost of capital). Opportunity cost.
 ② Renting cost for space. (warehousing space) or own
 f (value held, interest rate). Like 25% of item for one year.
 ↳ function.

* Inventory held in 3 places:

- ① at Plant (مخزن الشركة)
 - ② at warehouse (Destination). (مخزن العميل)
 - ③ in-transit. → في الطريق
- Diagram: Plant → time → Warehouse (WH).
 25% of value/year held (15% - 25%)

Problem 8 A company needs to select between two transportation modes rail and truck, to move goods from plant to WH with obj of minimizing total transportation cost and inventory cost.

علائق تجارية

لأنه إذا خزننا البضائع في أحد المراكز يمكن أن نوفر تكاليف أخرى

Data	Plant	WH.
safety stock	0	100 units

value of item	\$500/unit	\$512/unit	→ Handling of materials
space cost	\$20/unit.year	\$25/unit.year	→ Transportation

Rail: - Car capacity = 400 units.
 - transit time = 20 days
 - cost per shipment = \$1200

* Truck: - Truck capacity = 100 units → per shipment
 - transit time = 3 days
 - cost per shipment = \$700

* production rate at plant 10 units/day.

Demand at WH 10 unit/day.

Inventory holding cost rate 25% of value/year held

* Goal is to determine the optimal shipment size.

q (# of units) for each mode and the total annual cost associated with these shipment sizes.

Assumption: shippers will never ship more than a single carload (rail) or a single truckload (truck).

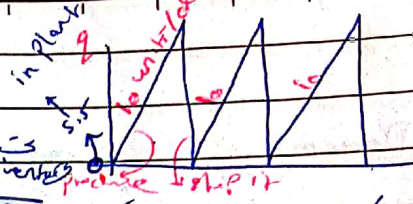
soln:

steps:

- [1] Determine annual inventory space cost at the plant.
- [2] " " " holding " " " "
- [3] " " " space " " " WH.
- [4] " " " holding " " " "
- [5] Determine in-transit inventory cost $\begin{cases} \rightarrow \text{for Rail} \\ \rightarrow \text{Truck} \end{cases}$
- [6] " transportation costs $\begin{cases} \rightarrow \text{Rail} \\ \rightarrow \text{Truck} \end{cases}$
- [7] total annual cost expenses $\begin{cases} \rightarrow R \\ \rightarrow T \end{cases}$
- [8] Determine optimal q for each mode.
- [9] choose mode.

Solution :-

1) space cost at plant $\Rightarrow$ 
annual space cost = $\frac{\$20}{\text{unit-year}} \times 9 \text{ units} = \20 / year.
 year 1 is
 \$/year 25



average = $\frac{Q}{2}$ → assurance — average is holding cost ← / — $\frac{Q}{2}$ → space cost

2) Hold.

2) Holding cost of plant.

~~- rate of charge per item of inventory held~~

at plant for a year = \$ 500 $\times$ 25% = 1.25 \$/unit year

~~- Avg memory level = 9~~

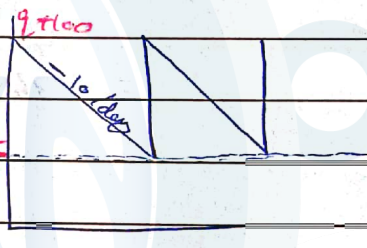
$$(125 \text{ g/unit} \cdot \text{year}) \left(\frac{2}{2} \text{ units} \right) = 62.5 \text{ g\$ / year.}$$

3) space cost at WH.

↳ depend on max. inventory level

~~max inventory level = $q + 100$ units~~

$$\text{Space Cost} = (\$25 / \text{unit} \cdot \text{year}) (q + 100) \text{ units} \quad \text{100} = 5.5 \text{ safety stock}$$

$$= (25q + 2500) \$/\text{yr.}$$


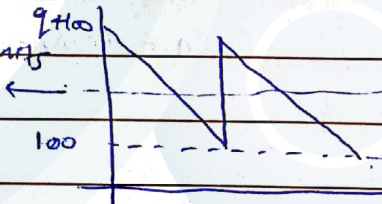
4) Holding cost at WH.

$\overleftarrow{\text{Avg inventory}} \quad \text{Avg inventory level} = 100 + \frac{9}{2} \text{ units}$

$\frac{1}{2} \times 100 = 50$

Dep or Inc
 1
 Holding
 Cost:

each item held on year charged at rate of \$ 512 * 25;
= \$ 128 / unit . year

$$\text{Holding cost} = \frac{\$128}{\text{unit} \cdot \text{yr}} * (100 + \frac{9}{2}) \text{ units}$$


5) Determine in transit inventory costs.

$$\text{Use } \frac{506 \$}{\text{unit}} = \frac{500 + 512}{2}$$



each item charged at $\frac{\$506}{\text{unit}} \times 25\%/\text{yr.} = \$126.5/\text{unit/yr.}$

For Rail: each item spends 20 days amount to be shipped for whole yr = production rate * period
 $= 10 \frac{\text{unit}}{\text{day}} \times \frac{365 \text{ day}}{\text{yr.}} = 3650 \frac{\text{unit}}{\text{yr.}}$

In transit cost = amount shipped * in transit time.

* in transit holding cost.
 $= 3650 \frac{\text{unit}}{\text{yr}} \times 20 \text{ days} \times \frac{1 \text{ yr}}{365 \text{ day}} \times 126.5 \frac{\$}{\text{unit/yr.}}$
 $= 25300 \$/\text{yr.}$

for Trucks

In-transit cost truck = $\left(3650 \frac{\text{units}}{\text{year}} \right) \times \left(3 \text{ days} \times \frac{1 \text{ yr}}{365 \text{ day}} \right) \times (126.5 \$/\text{unit/yr.})$
 $= 3,795 \$/\text{year.}$

④ Transportation cost.

Rail: every shipment cost = \$1200.

of shipments = $\frac{3650}{2}$ shipment/yr.
 $\rightarrow \text{2 trips if each is 1000 units}$

$$\text{Transportation Cost Rail} = \left(\frac{\$1200}{\text{shipment}} \right) * \left(\frac{3656 \text{ shipment}}{q \text{ yr}} \right)$$

$$= \frac{4,380,000}{q} \$/\text{yr.}$$

$$\Rightarrow \text{Transportation Cost for Truck} = \left(\frac{\$700}{\text{shipment}} \right) * \left(\frac{3656 \text{ shipment}}{q \text{ yr}} \right)$$

$$= \frac{2,559,200}{q} \$/\text{yr.}$$

$$7) * \text{Total annual cost} \Rightarrow \text{TCT}(q) = 20q + 62.5q + 25q + 2500 + 64q + 12800 + 25300 + \frac{4380000}{q}$$

$$= 171.5q + 40600 + \frac{4380000}{q}$$

for optimum $q \Rightarrow$ ~~Derive~~ $\Rightarrow (8)$ ~~Derive~~

from inventory costs from (in-transit) cost

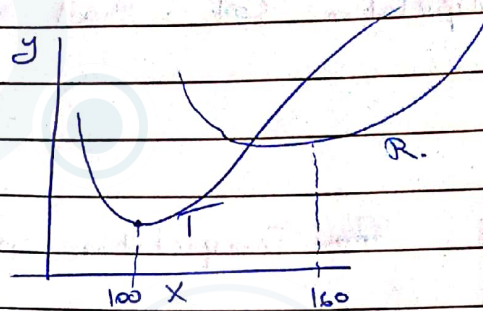
$$* \text{For Trucks:}$$

$$\text{TCT}(q) = 20q + 62.5q + 25q + 2500 + 64q + 12800 + 25300 + \frac{2559200}{q}$$

$$= 171.5q + 19095 + \frac{2559200}{q}$$

in Excel:

q	TCT	TCR
10	$= 171.5q + \dots$	
20		
	Expand	



8) optimal q for each mode.

Rail * $TCR'(q) = 171.5 + 0 - \frac{4380000}{q^2} = 0$

$$q_R = \sqrt{\frac{4380000}{171.5}} \approx 160 \text{ units}$$

(note: Rail's capacity is 160)

$$TCR(q_R = 160) = 171.5 * 160 + 40600 + \frac{4380000}{160}$$

$$= \$95,415 \text{ /yr.}$$

Truck * $TCT'(q) = 171.5 \frac{q}{2} - \frac{2555000}{q^2}$

$$q_T = \sqrt{\frac{2555000}{171.5}} \approx 122 \text{ units.}$$

(note: capacity is 122)

So I need 2 Trucks ← Capacity < q ← Truck

shipment cost = $2 * 700 \$ * \frac{3650}{q}$

$$= \frac{5110000}{q}$$

$$TCT(q_T = 122) = 171.5 * 122 + 19095 + \frac{5110000}{122}$$

$$= \$81,903$$

Inventory cost

In-transit cost

If maximum of Truck is optimum.

$$TCT(q_T = 100) = \$61,795 \Rightarrow \text{so this is minimum possible cost.}$$

(q on capacity of Truck)

$$TCT(q_T = 99) = \$61,881.58$$

So Truck is better than Rail (according to cost).

addition:

<u>Shipment</u>	<u>Inventory cost</u>	<u>Transp. cost</u>	<u>Total cost</u>
160 Rail	68,040	27,375	95,415
400	↑ 109,200	↓ 10,950	120,150
140	↓ 64,610	↑ 31,286	95,896

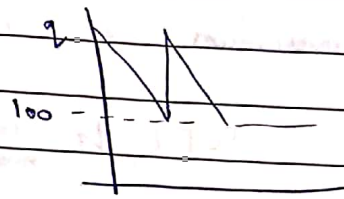
∴ Transportation Rates and Costs by mode.

* Fixed costs: infrastructure (port, ~~to~~ Equipment, right of way (w), airports, planes, ships, machine, vehicle, road)

* variable cost (operating): fuel, maintenance, driver, ...

<u>mode</u>	<u>Fixed</u>	<u>variable</u>	<u>Fixed cost components</u> <i>↳ why it's low or high</i>	<u>variable cost component</u>
(ships) water	MH	L	vehicle	Low speed, high capacity
Rail	H	L	rail roads, control systems	Fuel efficiency, fuel efficiency, small crew
Truck	L	H	Trailer, gross terminals	Drivers, fuel, maintenance
(planes) Air	H	MH	vehicle, terminals, facilities	Fuel, maintenance

$$\begin{aligned}
 \max &= 9 + 100 \\
 \min &= 100 = 5.5 \\
 \text{avg.} &= \frac{9 + 100 + 100}{2} = \frac{9}{2} + \frac{200}{2} \\
 &= \frac{9}{2} + 100
 \end{aligned}$$

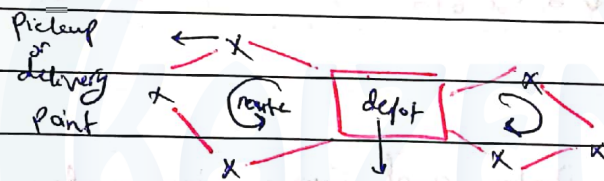


* Short-haul transportation (freight).

when pickup/delivery of goods in relatively small area using fleet not vehicles.

Unless stated otherwise, vehicles are stationed at single depot.

- Routes include several pickup and/or delivery point
- Routes performed in a single work shift.



ie: warehouse, port, terminal, plant itself.

* Decisions in short transportation:

- Strategic: where to locate the depot/warehouse "terminal". Location problem / facility location
- tactical: Fleet sizing (ie: $\Rightarrow$ how many trucks to have. (cars))
- operational: vehicle routing and scheduling problem "VRSP"
- L route: where each vehicle is responsible.

* we will focus on operational prob.

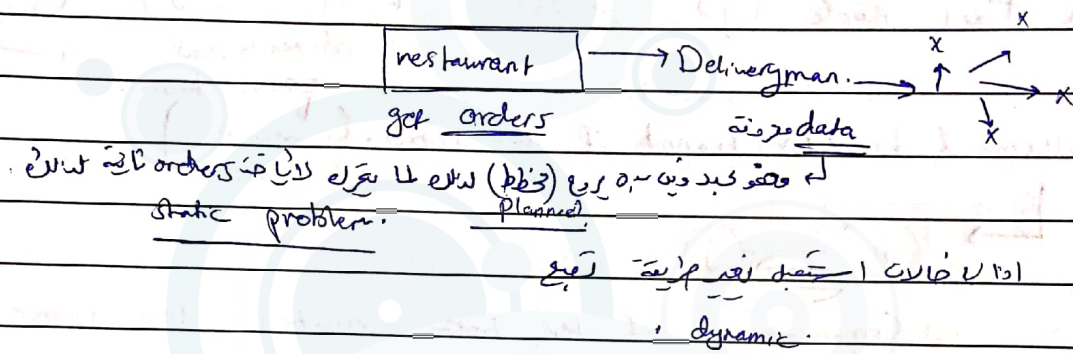
* according to data known beforehand type.

L static vehicle routing prob: all customers requests (location & amount of goods) is known in advance.

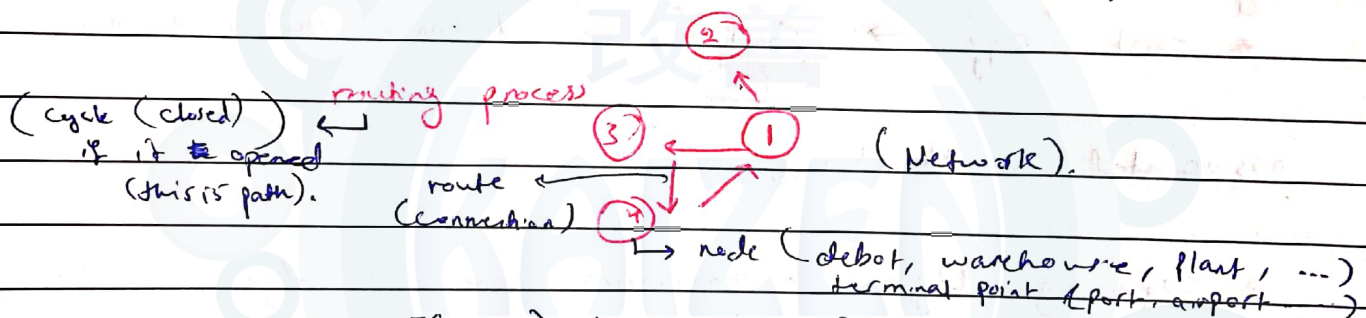
L Dynamic vehicle routing prob: (VRP) not all information is known in advance.

in DVRP - Routes planned for set of requests known in advance, dynamically updated to incorporate new requests.

*



* transportation prob are defined on graphs, which are symbolic representation of networks and their connectivity.

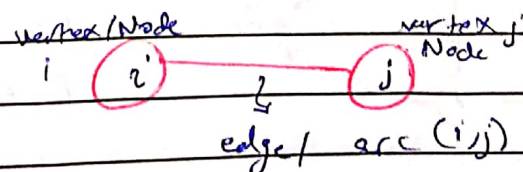


Graph: $G(V, E)$ is a set of vertices/nodes (V/N) connected by a set of edges/arcs (E/A).
Notation $G = (N, A)$.

- vertex: terminal point / intersection point of graph.

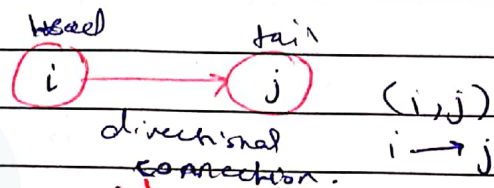
⇒ Represents 2 city, customer location, depot, road intersection.
First + Final Location.

- Edges: Link between two vertices Edges/arcs often referred to as (i, j) connected vertex i to vertex j .



- Arrow representation direction.

- * Head node i
- * Tail node (j)



- A summed bidirectional if no arrow. (↔ is 1)



(Symmetric if the both routes the same cost)

- Edges / arcs have number of characteristics:

- * Cost " c_{ij} " → Cost (Time, distance, fuel, Risk, ...)

associated with (i, j)

- * Capacity " U_{ij} " → maximum flow on edge (i, j) .

↳ traffic / amount of ...

** Order of a graph : number of nodes / vertices, $|V|$

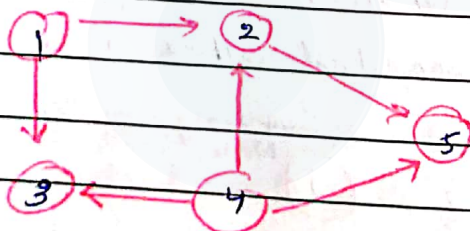
$V = \{1, 2, 3, 4, 5, \dots\} = \{\text{Amman, Aqaba, ...}\}$

$|V| = 5$

↳ as Listing

** Size of graph : number of edges $|E|$

Ex:



⇒ $G = (V, E)$

$V = \{1, 2, 3, 4, 5\}$

$E = \{(1, 2), (1, 3), (2, 5), (4, 2), (4, 3), (4, 5)\}$

order of $G = 5$ $|V|$

size of $G = 6$ $|E|$

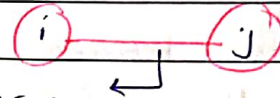
directional
non-directional

* Structural properties of graph:

- Undirected vs directed:

↳ Networks without specified direction.

a connection between $i \neq j$ implies a connection btw $i \neq j$.

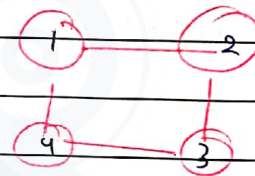


Also referred to as a

Symmetrical network. (Symmetrical edge, ...)

the same cost from $1 \rightarrow 2$ (or $2 \rightarrow 1$)

if differs $\rightarrow$ bidirectional & asymmetric.



Ex:



symmetric

- move in both direction.

- cost is the same in both. bidirectional.



asymmetric

- move in both directions.

- cost isn't equal. (3, 5) (bidirectional).

* In transportation problem; sometimes symmetry used to represent whether cost is same when traveling from i to j as when traveling from j to i .

- asymmetry example $\rightarrow$ traffic may be higher in one direction resulting in higher travel time.

Asymmetry is the cost of bidirectional is not the same

asymmetric

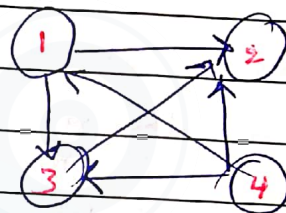
* symmetric & asymmetric both are bidirectional, cost that determine

which one of them.

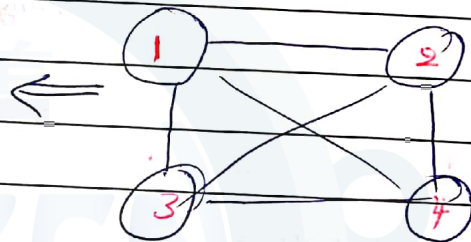
Final Conclusion:

sym. or asym. = bidirectional] in undirected
but directed just in one direction.

- Completeness: a graph is complete if an edge exists between every pair of vertices. (regardless of direction).



Complete undirected.



* Paths, Cycles, Trees:

For the following definition, assume there are (n) vertices in (V) and (m) edges in (E) .

Path: a path in G is a sequence of vertices $\{i_1, i_2, \dots, i_p\}$ such that

- $i_k \in V \quad \forall k = 1, \dots, p$

- i_k unique $\forall k = 1, \dots, p$ ← no vertex visits more than once.

- (i_k, i_{k+1}) or $(i_{k+1}, i_k) \in E$

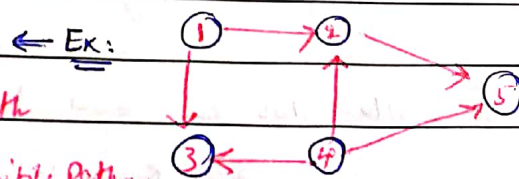
Path from 1 to 5:

$\{1, 2, 5\}$

feasible path

$\{1, 2, 4, 5\}$

not feasible path



Directed, not complete

edges $m = 6$

$\{1, 3, 5\}$

$\{1, 4, 5\}$ } not paths (not $(1, 4), (4, 3)$ in G)

$\{1, 2, 4, 3, 1, 2, 5\}$

- Directed path:

Additional condition: $(i_k, i_{k+1}) \in E \forall k=1, \dots, p-1$
is a feasible sequence of decisions for users.

according to cost we

decide which path to go (OR prob. (min cost))

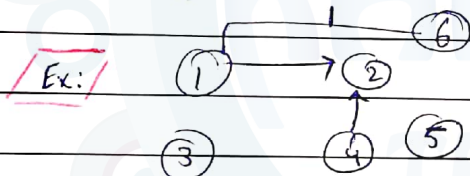
in previous ex, $\{1, 2, 5\}$ is a directed path $\Rightarrow$ feasible.

- Related concept: Connectedness

Connected: two vertices i & j are connected in G if there exists a path from i to j .

$\rightarrow$ regardless direction or feasibility.

- Adjacency: i & j connected by a path of length 1.



- nodes 1 and 4 are connected but not adjacent.

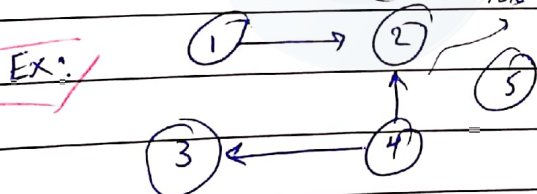
- nodes 1 and 2 are adjacent.

so By default connected

- nodes 1 and 6 are adjacent.

- A graph is connected if every pair of vertices in the graph are connected.

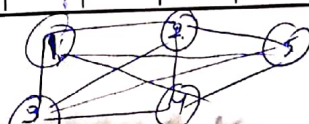
(not feasible $4 \rightarrow 2$ in)



Not connected.

(if 5 connected then path is connected).

(complete if $(1, 5) \rightarrow$ min path.) Not complete.



Connected path 2 nodes

② path (1, 4) ←

改善

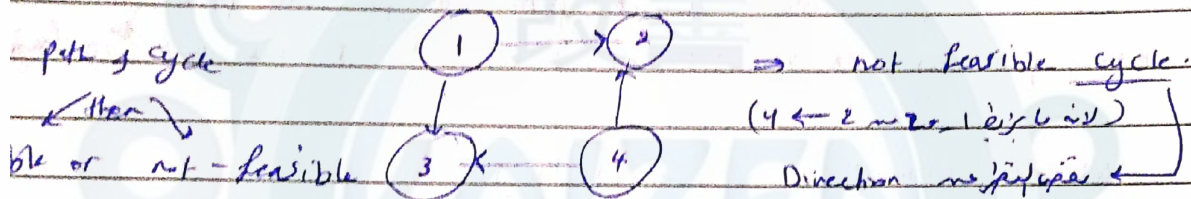
KAIZEN

TEAM

connected path for 2 nodes v_1, v_2
 (2) v_1 in path $p(1, 4)$ $\Rightarrow$ dir. path
 complete $\Rightarrow$ by default connected path.

Cycle

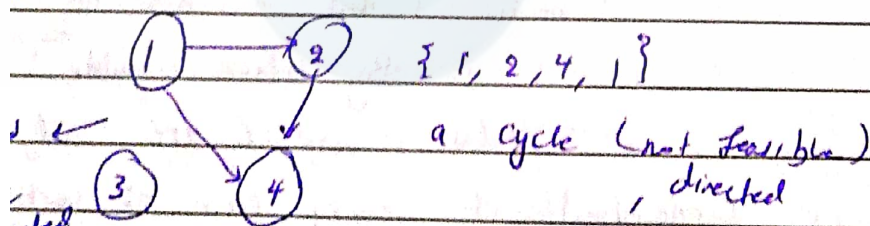
set of edges that form a closed loop in G ,
 you can begin walking at some vertex, follow
 only edges in the cycle regardless of their
 direction, then return to original vertex.



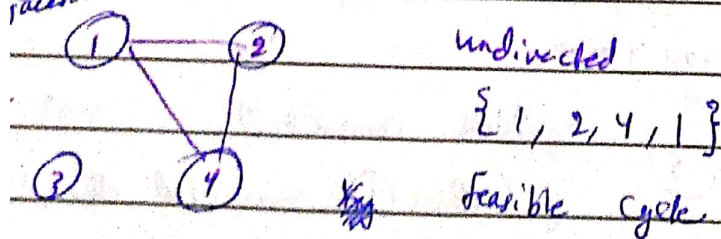
Direction $\Rightarrow$ not feasible cycle $\Rightarrow$

that - cycle is a sequence of vertices $\{i_1, i_2, \dots, i_p, i_1\}$
 $\rightarrow i_k \in V \quad \forall k=1, \dots, p$ (p : path)
 $\rightarrow i_k$ unique $\forall k=1, \dots, p$ (s. in sequence)
 (i_k, i_{k+1}) or $(i_{k+1}, i_k) \in E \quad \forall k=1, \dots, p-1$

$\Rightarrow$ either (i_p, i_1) or $(i_1, i_p) \in E$ (i.e. either feasible or no)

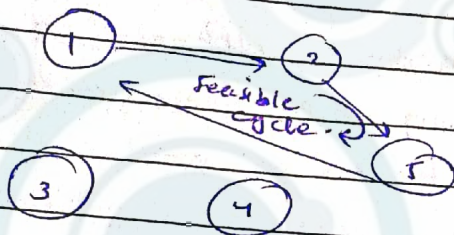


not
 recent

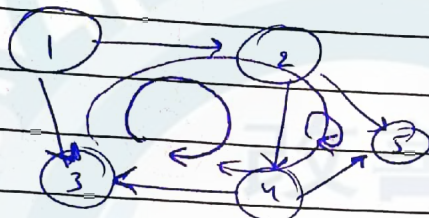


nodes in
 undirected cycle
 by default
 feasible cycle

Ex 1



Ex:



3 cycle? none is feasible

1-2-5 path

2-5-4-3-1-2

1-2-5-4-2 } cycle

→ cycle → short

(2-5-4-2) ← cycle given simplified rep

1-2-5-1 not cycle (5-1 not

have an edge)

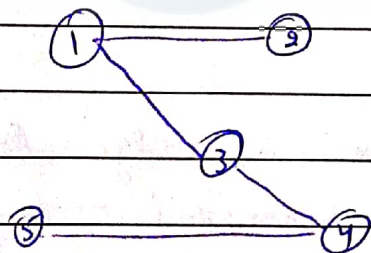
5-4-3-1 → path join
(arc) 5-1 no

* Tree:

is a collection of edges such that vertices are connected & no cycle exists.

Equivalent def: n vertices in the network. $\Rightarrow$ A tree is a set of $n-1$ edges such that all vertices in the network are connected.

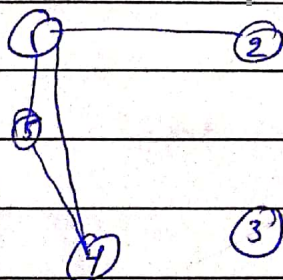
ex:



4 edges, 5 nodes (all connected)

$\Rightarrow$ tree ✓

ex:



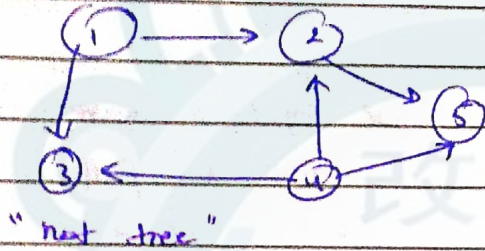
5 nodes & 4 edges but

not tree (there is a cycle

and (3) not connected)

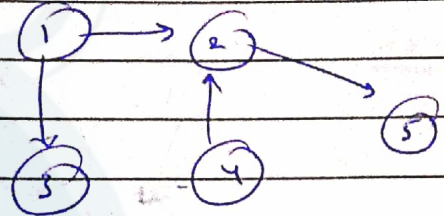
- Important property of a tree: defines for each pair of vertices, a unique (not necessarily directed) path between them. (feasible or not)

ex: Directed networks.



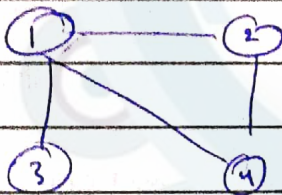
"not tree"

(edges cycle in it)
nodes are not

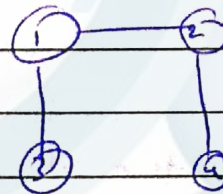


"Directed tree"

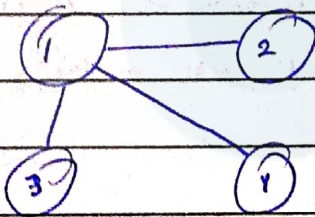
ex: Undirected network.



"not tree"



"yes"



"yes"

- what happens if you remove an edge from tree?
some vertex is no longer connected $\rightarrow$ graph is Tree-edge
= unconnected (not connected graph).

- if you add an edge to tree?
creates a cycle $\rightarrow$ no longer tree.

* minimum cost path models :

many transportation decisions models require finding the min cost path(s) between pair(s) of vertices.
⇒ Cost can be time, distance, \$, risk.

* Applications:

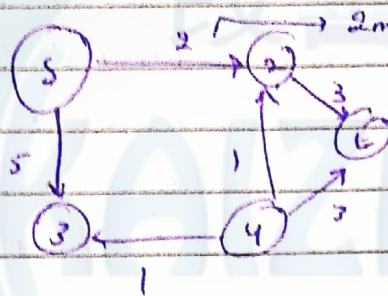
- personal travel : road network. ⇒ person want to determine what's the minimum time path between origin + destination.
- Global supply chain: Given the network model for a ~~representing~~ shipper ^{representing} its full set of transportation services for a particular commodity.
Q: determine the min. cost (time) transport option from origin to destination.

* min cost path prob. Variants (times):

- single-pair shortest path problem.
⇒ Find the shortest path between a single source node "S", and destination node "t".
- single-source shortest path problem.
⇒ to find shortest path between single source node "S" and all other vertices, nodes.
- single-destination SP problem:
⇒ to find shortest path from all vertices to a given destination node "t".
- All-pair shortest path problem "SPP".
⇒ to find shortest path between all pair of vertices.

= Formulation definition & (regardless of types recently defined)
 Given a graph $G = (V, E)$ with costs c_{ij} for each $(i, j) \in E$, a source node "s", and a destination node "t", find the path p from s to t that minimizes "total cost" for the path.

ECM
 (KIDep)



2 mins, 2 hrs, 2\$, ... (any unit of cost)

* Path from s to t :

$\{s, 2, t\} \rightarrow \text{cost} = 5$

$\{s, 3, 4, t\} \rightarrow \text{cost} = 9$

$\{s, 2, 4, t\} \rightarrow \text{cost} = 6$

etc. (regardless of feasibility)

* Solving minimum cost path problem.

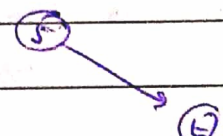
1. Dijkstra's algorithm: Single-pair, single-source, single-destination.

To find single source shortest path (SP).

- requires $c_{ij} \geq 0$ (true)

(assuming path exists with all (-ve) negative cost)

remember all cost of $v \rightarrow t$



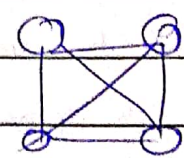
(optimal path)
 (1st step)
 optimum path

- pros: ① Fast for dense network (caching edges)
 ② can be truncated, if path of interest has been found.

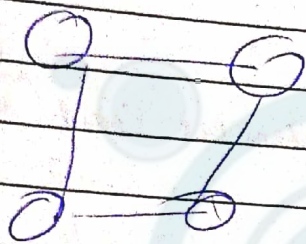
(caching edges)
 we should write a code to solve this prob on software by this algorithm.
 ↳ needs programming

(dense network)

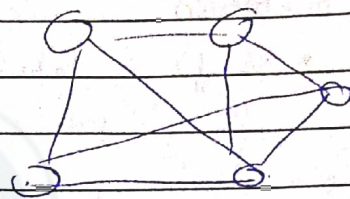
edges = 6
 nodes = 4



- cons: Alternative methods faster for sparse network.



(sparse network)



(dense network.)

- preparing is needed
- for efficient implementation.

2. Bellman Ford Algorithm: single-source shortest path, allows (not requires) $c_{ij} \leq 0$, paper's modification.

* pros:

- Fast for sparse networks
- simple to implement

↳ performance ↑

* Cost if I pay it
"loss" (cost), if I gain it (the)

* cons:

- can't be truncated.
- may be slow on dense networks

- route: we should return to source node. (same of cycle)

- path: we should go from source node to destination node.

* Dijkstra algorithm:

it's a labeling algorithm in which, at each iteration a different vertex p is given a permanent label $v(p)$ that indicates the cost of the shortest path from s to p .

⇒ Assumption: $c_{ij} \geq 0 \forall (i,j) \in E$ ↳ in terms of cost.
↓
Edges that belong to network

• Notation:

• $V(j)$: label for vertex j and denotes cost of path from s to j .

• $\text{pred}(j)$: predecessor of node j on shortest path from s to j .

• PERM : set of permanently labeled nodes.
($\overline{\text{PERM}}$ and permanently unlabeled nodes)

$\hookrightarrow$ at each iteration one permanent and other not.

• Initialization:

• $V(j) = \begin{cases} 0, & j = s \\ \infty, & j \neq s \end{cases} \Rightarrow$ very expensive cost in initialization

of program cause I solve min prob. very

• $\text{pred}(j) = \begin{cases} 0, & j = s \\ -1, & j \neq s \end{cases} \rightarrow$ ~~initial~~ unlabeled node cost

• $\text{PERM} = \{s\}$, $\overline{\text{PERM}} = V$

$\hookrightarrow$ list of permanent nodes $\Rightarrow$ empty $\rightarrow$ ~~unlabeled~~ node is

• Iteration's while $\overline{\text{PERM}} \neq \emptyset$ "not empty"

$\Rightarrow$ job node is

1. let $p \in \overline{\text{PERM}}$ be node for which $V(p) = \min\{V(j) \mid j \in \overline{\text{PERM}}\}$

2. $\text{PERM} \leftarrow \text{PERM} \cup \{p\}$

3. $\overline{\text{PERM}} \leftarrow \overline{\text{PERM}} \setminus \{p\}$ "exclude"

4. For all $(p, j) \in E$, $j \in \overline{\text{PERM}}$ leading from p to j

if $V(p) + c_{ij} < V(j)$ then

$V(j) = V(p) + c_{ij}$

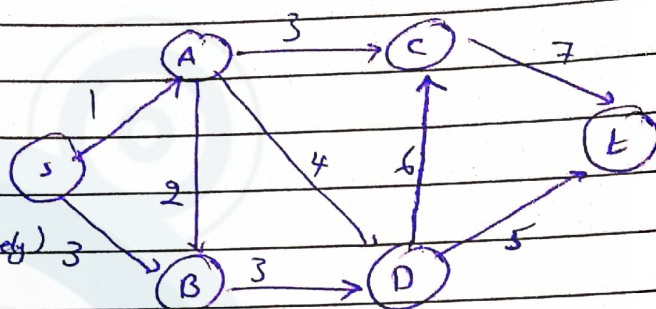
$\text{pred}(j) = p$

"else do not anything"

5.

$V(j) \rightarrow$ Cost of shortest path from s to j .

$prev(j) \rightarrow$ node before (immediately) j in path.



$v(j) \leftarrow [\text{pred}(j)]$ for each node.

iteration.

iteration.	S	A	B	C	D	E	P	PERM	PERM
initialization.	0 [0]	∞ [-1]	∞ [-1]	∞ [E]	∞ [-1]	∞ [-1]	∞ [-1]	{}	S, A, B, C, D, E

$$3 + 0 \leq 3 \leftarrow (s_p + r(5)) \leq r(8) \leftarrow$$

$0[s] \quad 1[s] \quad 3[s]$

possible nodes to go from s

$\begin{array}{c} S \\ \text{Widely needed} \\ \text{Sindhu} \end{array} \quad \leftarrow \quad \begin{array}{c} S \\ S \\ S \end{array} \quad \begin{array}{c} A, B, C, D \\ E \end{array}$

~~11/11/11~~

$B, A \sim \dots \sim A$
 $S_1 A$
 B, C, D, E

$\therefore VCA + C_{AC} = 1 + 3 = 4 < V(C) \checkmark \therefore$ Change cost of C to be 4

4[A] 5[A] (A → B) (A → B) (A → B)

Cost of
Material

in iteration "3" if I take from $B \rightarrow d$, cost = 6 which is greater from $A \rightarrow D$ so I don't do anything.