

ch 12

* Rectilinear: straight line motion.

* Distance: s ; scalar quantity

- Velocity ① $V = \frac{ds}{dt}$ $V_{avg} = \frac{\Delta s}{\Delta t}$ $V_{speed} = \frac{s}{t}$ also a scalar quantity

$a_{avg} = \frac{\Delta v}{\Delta t}$ ② $a_{instantaneous} = \frac{dv}{dt} \rightarrow \underline{ads = v dv}$ important equation without time.

12.5 prob 8

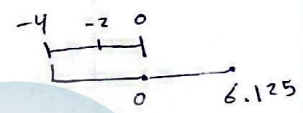
$V = 3t^2 - 6t$ m/s, located on origin, distance $t = 3.5$ s traveled when

V_{avg} , $V_{sp, avg}$

* $V = \frac{ds}{dt} \rightarrow ds = v dt \rightarrow \int_0^s ds = \int_0^t (3t^2 - 6t) dt$

$s = t^3 - 3t^2$ m

t	0	1	2	3	3.5
s	0	-2	-4	0	6.125

→ 

* distance $t = \sum s = 14.125$ m we need to check first.

* لا نأخذ المسافة في الـ t التي فيها غير ضيق الجسم الجاه $V=0$ عند هاتين $t=2$ و $t=0$ so yes it's correct when $t=2$.

- So when $V=0$ $t=2$ و 0

$V_{avg} = \frac{\Delta s}{\Delta t} = \frac{6.125}{3.5} = 1.75$ m/s $\rightarrow V_{sp/avg} = \frac{14.125}{3.5} = 4.04$ m/s

* acceleration equations: $a_{constant}$

* $V_f = V_i + a_c t$

* $s = s_0 + V_0 t + \frac{1}{2} a_c t^2$

* $V_f^2 = V_i^2 + 2a_c (s_f - s_i) \rightarrow$ no time in these equation.

LH / 2.

example 12.4

$\begin{array}{|l} \text{B } v_B = 0 \\ \text{A } v_A = 75 \\ \text{C, } v_C = ?? \\ \text{O} \end{array}$
 $\begin{array}{|l} s_B = ? \\ s_C = ? \end{array}$

* no time

* $v_f^2 = v_o^2 + 2ac(s_f - s_i) \Rightarrow v_B^2 = v_A^2 - 2g(s_B - s_A)$

* $ac = g = 9.81 \text{ m/s}^2$

* it will be (-)

Part (A)

$0 = 75^2 - 2(9.81)(s_B - 40)$

$s_B = 327 \text{ m.}$

Part (B)

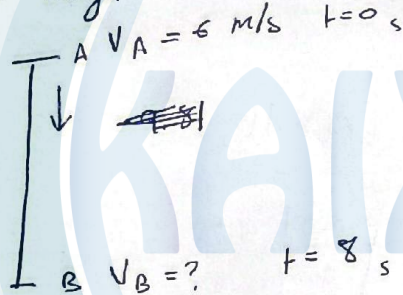
$\Rightarrow v_c^2 = v_B^2 - 2g(s_c - s_B)$

$= 0 - 2(9.81)(0 - 327)$

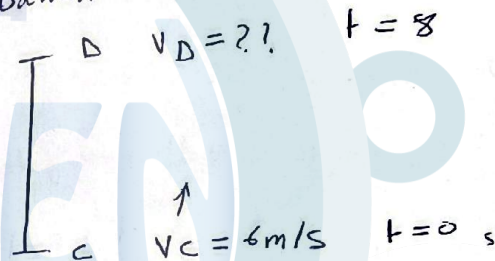
$v_c = 80.1 \text{ m/s} \downarrow$

Prob (12-22) * constant speed = acceleration is zero

Sand bag



ballon



$v_f = v_i + a_c t$

$v_B = +6 - 8(9.81)$

~~$= -84.5 \text{ m/s}$~~

$= 72.5 \text{ m/s} \downarrow$

$v_f = v_i + a_c t$

$v_D = 6 + 8(9.81)$

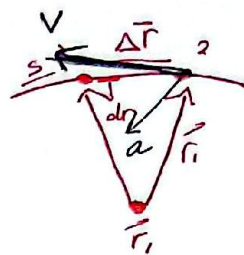
$= 84.5 \text{ m/s}$

12.4

general curvilinear Motion:

$$\bar{v}_{avg} = \frac{\Delta \bar{r}}{\Delta t}, \quad \bar{v}_{inst} = \frac{d\bar{r}}{dt}$$

$$a_{inst} = \frac{d\bar{v}}{dt}$$



12.5: Rectangular components.

12.7: Normal and Tangential:

12.8: Cylindrical components. X not included.

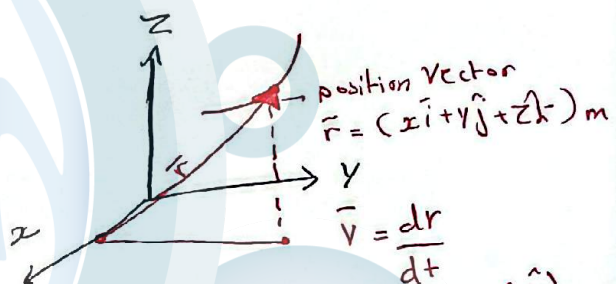
* velocity is always tangent to the curve, a is always to inside the curve.

12.5: Rectangular components.

$$\bar{a} = \frac{d\bar{v}}{dt} = \frac{d^2\bar{r}}{dt^2}$$

$$\bar{a} = (\ddot{x}\hat{i} + \ddot{y}\hat{j} + \ddot{z}\hat{k}) \text{ m/s}^2$$

$$\bar{a} = (a_x\hat{i} + a_y\hat{j} + a_z\hat{k}) \text{ m/s}^2$$



$$\bar{v} = \frac{d\bar{r}}{dt} = (\dot{x}\hat{i} + \dot{y}\hat{j} + \dot{z}\hat{k}) \text{ m/s}$$

$$\dot{x} = \frac{dx}{dt} = \bar{v}_x$$

$$\dot{y} = \frac{dy}{dt} = \bar{v}_y$$

$$\dot{z} = \frac{dz}{dt} = \bar{v}_z$$

ex-12.9

$$x = 8t$$

$$y = \frac{x^2}{10}$$

we need v, a when t=2s,

* First position vector?

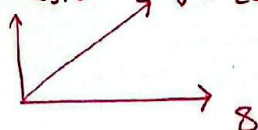
$$\bar{r} = (x\hat{i} + y\hat{j}) \text{ ft}$$

$$\bar{r} = (8t\hat{i} + \frac{(8t)^2}{10}\hat{j}) \text{ ft}$$

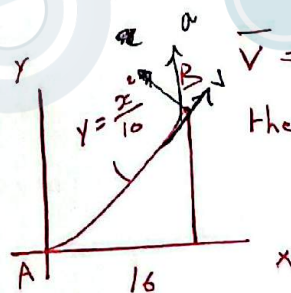
$$\bar{v} = \frac{d\bar{r}}{dt} = (8\hat{i} + 12.8t\hat{j}) \text{ ft/s}$$

$$|\bar{v}| = \sqrt{8^2 + (12.8(2))^2} = 26.8 \text{ ft/s}$$

* to find direction



$$v = 26.8, \quad \tan^{-1}\left(\frac{25.6}{8}\right) = 92.6$$

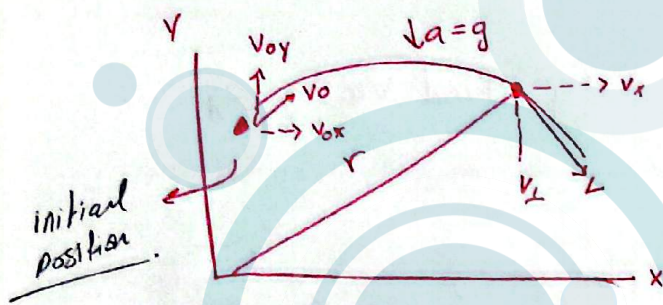


$$\bar{v} = (v_x\hat{i} + v_y\hat{j} + v_z\hat{k}) \text{ m/s}$$

these are Rectangular components

$$\bar{a} = \frac{d\bar{v}}{dt} = (12.8\hat{j}) = 12.8 \text{ ft/s}^2 \quad \theta = 90^\circ$$

12.6) Motion of projectile.



$$\text{Range} = x_f - x_0$$

* Horizontal Motion : $a_c = 0$

$$v_f = v_0 + a_c t, \quad v_x = (v_0)_x$$

$$x = x_0 + v_0 t + \frac{1}{2} a_c t^2, \quad x_f = x_0 + v_{0x}(t) \rightarrow$$

$$v_f^2 = v_0^2 + 2(a_c)(x - x_0), \quad v_x = (v_0)_x$$

$$x_f - x_0 = (v_0)_x t$$

$$x_f - x_0 = \text{Range}$$

$$\text{Range} = (v_0)_x t$$

* Vertical Motion : $a_c = -9.81$

$$v = v_0 + a_c t$$

$$y = y_0 + v_0 t + \frac{1}{2} a_c t^2$$

$$v^2 = v_0^2 + 2a_c(y - y_0)$$

EXC - 12.11

$$v_{0y} = 0, \quad v_{0x} = 12, \quad t = 0$$

$$y_0 = 0, \quad y_f = -1\text{m}, \quad x_0 = 0, \quad x_f = R \quad | \quad \text{Find } t \text{ and Range}$$

* Will use this equation

$$y = y_0 + (v_0)_y t + \frac{1}{2} a_c t^2, \quad \text{Find } t$$

$$x = x_0 + (v_0)_x t$$

Find Range

$$\text{Range} = (v_0)_x t$$

* 12-85 Prob

$$t = 2.5 \text{ s}$$

$$y_0 = 0 \quad y_f = -1.2 \text{ m} \quad x_0 = 0 \quad x_f = 50$$

Find v_a , θ_A

$$* x_f = x_0 + (v_0)_x t \Rightarrow 50 = 0 + (v_0)_x (2.5) \quad v_{0x} = 20 \text{ m/s}$$

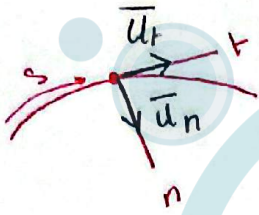
$$* y_f = y_0 + v_{0y} t + \frac{1}{2} a t^2 \Rightarrow -1.2 = v_{0y} (2.5) + \left(\frac{1}{2}\right) (-9.81) (2.5)^2$$

$$v_{0y} = ~~24.8~~ 12.7$$

$$v = ~~24.8~~ 23.7$$

$$\tan^{-1} \left(\frac{12.7}{20} \right) = 32.41^\circ$$

12.7 - Curvilinear Motion: Normal and Tangential component.



t-n: non-fixed coordinate system

$$v = \frac{ds}{dt}$$

$$\vec{v} = \frac{ds}{dt} (\vec{u}_t) \rightarrow \text{velocity is always tangent to the curve.}$$

$$\vec{a} = \frac{d(\vec{v})}{dt} = \frac{d(v\vec{u}_t)}{dt} \rightarrow \text{use product rule:}$$

$$\vec{a} = \frac{dv}{dt} \vec{u}_t + v \frac{d\vec{u}_t}{dt} \rightarrow \vec{a} = \underbrace{a_t \vec{u}_t}_{\text{change in speed}} + \underbrace{v \frac{d\vec{u}_t}{dt}}_{\text{change in direction}}$$

$$\vec{a}_{\text{tot}} = a_t \vec{u}_t + \frac{v^2}{\rho} \vec{u}_n \quad \rho = \text{radius of curve.}$$

$$\frac{v^2}{\rho} = a_n \quad \text{if } a_n = 0 \text{ only straight line.}$$

12-120 Prob

$$a_t = 0.5e^t, \quad s = 18, \quad \rho = 30 \text{ m}$$

$$a = \sqrt{a_t^2 + a_n^2}$$

$$\int dv = \int 0.5e^t dt \Rightarrow v = 0.5(e^t - 1) \Rightarrow v = 19.85 \quad \checkmark$$

$$ds = v dt \Rightarrow \int ds = \int 0.5(e^t - 1) dt \xrightarrow{18} \int_0^{18} ds = \int_0^t 0.5(e^t - 1) dt \Rightarrow t = 3.7 \text{ s} \quad \checkmark$$

$$a_t = 0.5e^t \quad t = 3.7 \rightarrow \boxed{a_t = 20.35 \text{ m/s}^2} \quad \checkmark$$

$$a_n = \frac{v^2}{\rho} = 13.14 \text{ m/s}^2 \quad \checkmark$$

$$a = \sqrt{a_t^2 + a_n^2} = 24.2 \text{ m/s}^2$$

220/2

$$\rho = \frac{\left[\left(1 + \left(\frac{dy}{dx} \right)^2 \right)^{3/2} \right]}{d^2y/dx^2}$$

الأصل ما نستخدمها غير
إذا اضطررنا

12-124 Prob)

$$y = 0.4x^2$$

$$x_A = 2 \quad y_A = 16$$

$$y = 8$$

$$\frac{dv}{dt} = a_t = 4 \text{ m/s}^2$$

$$a = \sqrt{a_t^2 + a_n^2}$$

$$a_n = \frac{v^2}{\rho}$$

$$\rho = \frac{\left[\left(1 + \left(\frac{dy}{dx} \right)^2 \right)^{3/2} \right]}{d^2y/dx^2}$$

$$\rho = \frac{\left[\left(1 + (1.6)^2 \right)^{3/2} \right]}{0.8} \quad \rho = 8.4$$

$$a = 8.6 \text{ m/s}^2$$

12-127 Prob

$$v_t = 20 \text{ m/s}$$

$$\rho = 29.62$$

$$a_{tot} = 14$$

$$a_n = 14 \sin 75 = 13.5 \text{ m/s}^2 \quad a_t = 14 \cos 75 = 3.6 \text{ m/s}$$

$$a_n = \frac{v^2}{\rho} \Rightarrow 13.5 = \frac{20^2}{\rho} \Rightarrow \rho = 29.62$$

$$y = 0.4x^2$$

$$y' = 0.8x = 1.6$$

$$y'' = 0.8 = 0.8$$

$$a_n = 7.6 \text{ m/s}^2$$

16.1 : ✓

16.2: Translation

constant y, x coordinate system, Translating coordinate systems.

$$* r_{B/A} \Rightarrow * r_A + r_{B/A} = r_B \rightarrow v = \frac{dr}{dt}$$

$$* r_{B/A} = r_B - r_A \rightarrow v_A = v_B \quad / \quad a_A = a_B$$

16.3 : Rotation about a Fixed Axis: use right hand method.

angular velocity $\Rightarrow \omega = \frac{d\theta}{dt}$ rad/s , $\alpha = \frac{d\omega}{dt} \rightarrow$

- $\rightarrow$ acceleration / تسريع الزاوي
- $\rightarrow$ deceleration / تباطؤ الزاوي

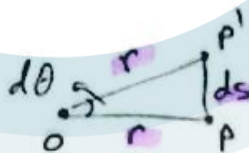
* constant Angular acceleration

$$v) \quad W = W_0 + a_c t$$

$$2) \theta = \theta_0 + \omega \cdot \dots$$

3) ...

* Motion of P



$$\tan \theta = \frac{ds}{r}$$

$\theta = \tan^{-1} \frac{v_y}{v_x}$

$$\text{so } d\theta = \frac{ds}{r} \Rightarrow s = r\theta$$

$$\frac{ds}{dt} = \frac{rd\theta}{dt}$$

$\Rightarrow v = r\omega$ $\rightarrow$ angular velocity

tangent $\leftarrow$
to curve

$$\frac{dv}{dt} = a_t = \frac{dwr}{dt} = r \frac{dw}{dt}$$

$$R_t = r \infty$$

* 3d =

$$\vec{V} = \vec{W} \times \vec{r}_P$$

- you learn by mistakes. Dr Yazon

$$a_n = V^2 / R \Rightarrow a_n = \frac{\omega^2 r^2}{r} \Rightarrow a_n = \omega^2 r$$

time rate change in direction.

$$\vec{V} = \vec{\omega} \times \vec{r}_P$$

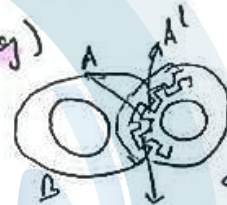
$$a = \frac{d\omega}{dt} \times r_P + \frac{dr_P}{dt} \times \omega \Rightarrow a_{\text{resultant}} = \alpha \times r_P + \omega \times (\omega \times r_P)$$

✓ نتيجة

$$a = a_{\text{resultant}} = \alpha \times r - \omega^2 r$$

* r_P : it is any position vector from center to P if we have angle ($r_P \sin \theta$)

- two rotating bodies (Meshing)



Meshing point

$$(a_{t_B})_A = (a_{t_C})_{A'}$$

* for tangential acceleration $r \alpha_B = r \alpha_C$

$$(V_B)_A = (V_C)_{A'}$$

$$(\omega r)_B = (\omega r)_C$$

* normal accelerations are not equal

* هيك سيج التناظر خلص

L22 Mech
F16-6

$\omega_{0A} = 0$
 $\omega_{0B} = 0$ } ~~start~~ starting from rest.

$$\alpha_A = 4.5$$

$$v_P = \omega_D r_D \Rightarrow \omega_D = \omega_B$$

$$v_A = v_B$$

$$\omega_A r_A = \omega_B r_B$$

$$(13.5)(0.075) = \omega_B(0.225)$$

$$\omega_B = 4.5 \text{ rad/s}$$

$$\omega_B = \omega_D$$

$$v_P = 4.5 \times 0.125 = 0.562 \text{ m/s}$$

مربوطين ببعض الآخر
For $\theta \Rightarrow s = r\theta \Rightarrow s = r\theta_D$, $\theta_D = \theta_B$

$$\theta_B = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$
$$= 0 + 0 + \frac{1}{2} \alpha_B (3)^2 \Rightarrow$$

$$\theta_B = 6.75 \text{ rad/s}$$

$$s = (0.125)(6.75) = 0.844 \text{ m}$$

$$\omega_A = \omega_{0A} + \alpha_A t$$
$$\omega_A = 0 + 4.5(3)$$
$$\omega_A = 13.5 \text{ rad/s}$$

سؤال مع ربط دول
اندر الاستابتة وضوابطها

$$\alpha_A r_A = \alpha_B r_B$$

$$\alpha_B = 1.5$$

222/2

Prob 16-20

$$\alpha_A = 2t^3$$

~~not constant~~

not constant acceleration

$$(w_A)_0 = 20$$

$$V_B \text{ at } t=2 \Rightarrow \underline{V_B = w_B r_B} \Rightarrow (V_B)_B = (V_A)_A$$

$$w_B r_B = w_A r_A$$

we can find it first.

$$w_B (0.15) = 36 (0.05)$$

$$w_B = 12 \text{ rad/s}$$

~~$$w_A = \int \alpha_A dt = \int 2t^3 dt = \frac{2t^4}{4} = \frac{t^4}{2}$$~~

$$w_A = \int \alpha_A dt = \int 2t^3 dt = \frac{2t^4}{4} = \frac{t^4}{2}$$

$$-20 + w_A = 16 \Rightarrow w_A = 36$$

Prob 16-35

$$w = 14 \text{ rad/s}$$

we need to find v and a for point C

unit vectors w is $\frac{1}{\sqrt{2}} \hat{j}$

$$\vec{v} = \vec{w} \times \vec{r}_C$$

$$\vec{u}_{OA} \Rightarrow \vec{w}_{OA}$$

$$\vec{r}_C \text{ from origin} = (-0.3\hat{i} + 0.4\hat{j})$$

$$\vec{u}_{OA} = \frac{\vec{r}_{OA}}{|\vec{r}_{OA}|} = \frac{-0.3\hat{i} + 0.2\hat{j} + 0.6\hat{k}}{0.7} = \vec{u}$$

$$\vec{w}_{OA} = \left(\frac{-0.3\hat{i} + 0.2\hat{j} + 0.6\hat{k}}{0.7} \right) (14) = (-6\hat{i} + 4\hat{j} + 12\hat{k})$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -6 & 4 & 12 \\ -0.3 & 0.4 & 0 \end{vmatrix}$$

$$= -4.8\hat{i} - 3.6\hat{j} - 1.2\hat{k}$$

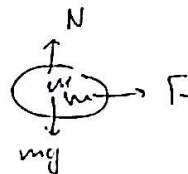
$$a_c = \frac{v_c^2}{r_c} + w_c \times (w_c \times \vec{r}_c)$$

$$= (38.4\hat{i} - 64.8\hat{j} + 40.8\hat{k}) \text{ rad/s}^2$$

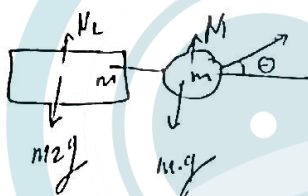
Ch 13: Kinetic

(the cause of the moment $\rightarrow$ Force $\mid \Sigma F = ma$)

13.2 1) system composed of one particle:

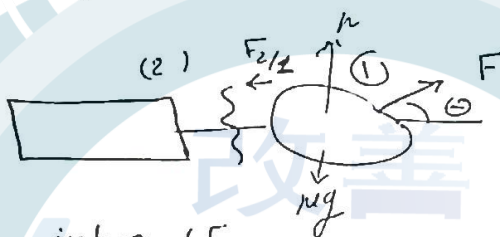


13.3) system composed more than one particle:



$$\rightarrow \Sigma F_x = m_1 a_1 + m_2 a_2$$

$$F \cos \theta = (m_1 + m_2) a_x$$



$F_{2/1}$ = internal force.

$$\rightarrow \Sigma F_x = m a_x$$

$$F \cos \theta - F_{2/1} = m_1 (a_x)$$

13.4) equations of Motion, Rectangular coordinates.

1) FBD (example) 13.2



$$\rightarrow \Sigma F_y = m a_y$$

$$-mg = m a_y \Rightarrow (10)(-9.81) = 10 a_y$$

$$a_y = -9.81 \text{ m/s}^2$$

$$V_0 = 50 \text{ m/s}$$

$$V_f = 0 \text{ m/s}$$

(use constant acceleration equation)

$$V_f^2 = V_0^2 + 2a(\Delta s)$$

$$0 = 50^2 + 2(-9.81)\Delta s \rightarrow (s=0)$$

$$\Delta s = 127 \text{ m (height)}$$

$\Delta s = 113.5 \text{ m}$
 هذا الارتفاع الذي قبله الجسم
 وجود F_D فقد الارتفاع

$$b) \Sigma F_y = m a_y$$

$$-mg - F_D = m a_y$$

$$-10(9.81) - 0.01 V^2 = 10 a_y \Rightarrow a_y = -(0.001 V^2 + 9.81) \text{ m/s}^2$$

When we don't have F_D

$$a ds = V dV \Rightarrow \int_0^s ds = \int_{50}^0 \frac{V}{a} dV \Rightarrow \int$$

Prob 13-26:

$$1.5 \text{ Mg} \rightarrow 1500 \text{ kg}$$

$$F = 4.5 \text{ kN}$$



$$\rightarrow F_x = m a_x$$

$$F - R = m a_x$$

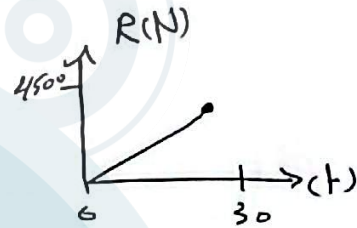
$$4,500 - R = 1500 \times a_x$$

$$R = (1500 \text{ N}) \Rightarrow \underline{4500 \text{ N}}$$

$$V = (-0.05t^2 + 3t) \text{ m/s}$$

$$a = \frac{dv}{dt} = -0.1t + 3 \text{ m/s}^2, t = 30$$

$$a = -0.1(30) + 3 \Rightarrow a = 0$$



改善

KAIZEN
TEAM

Mech L26

before this lecture go back : مراجعة

and solve Prob 13-5 and 13-4 they were mentioned in the previous lecture L25

ex 13.6

$$\sum F_a = ma \quad N \sin \theta = m a_n \Rightarrow N \sin \theta = m v^2 / \rho \quad (1)$$

$$+ \uparrow \sum F_b \Rightarrow N \cos \theta - mg = 0 \quad N \cos \theta = mg \quad (2)$$

divided one by 2

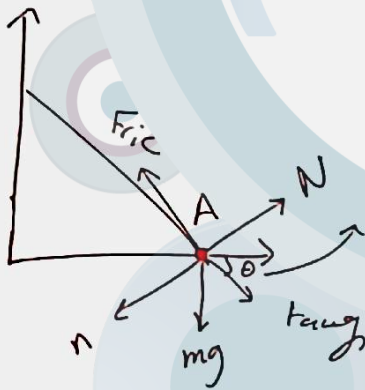
$$1/2 = \tan \theta = v^2 / \rho g \quad \theta = \tan^{-1}(v^2 / \rho g) \quad \text{كل ما زادت السرعة بتزيد}$$

Prob 13-69

$$a_t = 3 \text{ m/s}^2 \quad m = 0.8 \quad m = 800 \text{ kg} \quad v_f = 9 \text{ m/s}$$

$$y = 20 \left(1 - \frac{x^2}{400} \right)$$

We can know the angle from the slope.



$$\theta = 26.57$$

$$\frac{dy}{dx} = -0.00132x = -80 = -0.5$$

$$\tan^{-1}(-0.5) = 26.57^\circ$$

$$\sum F_t = ma_t$$

$$-Fric + mg \sin \theta = ma_t$$

$$-Fric + 800(9.81) \sin 26.57 = 800(3)$$

$$Fric = 1.1 \text{ kN}$$

$$\sum F_n = ma_n \rightarrow -N + mg \cos \theta = m v^2 / \rho$$

$$-N + 800(9.81) \cos 26.57 = \frac{800 a}{223.6}$$

$$N = 6.729 \text{ kN}$$

We need to find ρ by this equation:

$$\rho \left(1 + \left(\frac{dy}{dx} \right)^2 \right)^{3/2} = 223.6$$

$$y = 20 \left(1 - \frac{x^2}{400} \right) \leftarrow \frac{dy}{dx} = -0.00132x$$

Chapter 14) Kinetics of a particle: work and Energy.

$$du = F ds \cos \theta = \vec{F} \cdot d\vec{r} \quad \theta = 90^\circ, \text{ the work is zero.}$$

$$* U_{1-2} = \int_{s_1}^{s_2} F \cos \theta ds \quad \begin{array}{l} \nearrow \theta \text{ is constant} \rightarrow \text{rectilinear.} \\ \searrow \theta \text{ is not constant} \rightarrow \text{curvilinear.} \end{array}$$

— Work of a constant force, θ is constant:

$$* U_{1-2} = F_c \cos \theta (s_2 - s_1)$$

— Work of a weight:

$$U_{1-2} = -W \Delta y \rightarrow \text{because we care of vertical distance only.}$$

$$W = mg$$

— Work of Spring Force:

$$U_{1-2} = -\left(\frac{1}{2}k s_2^2 - \frac{1}{2}k s_1^2\right), \text{ it is usually negative.}$$

$k = \text{Spring stiffness}$

$$U_{1-2} = \frac{1}{2}k (s_1^2 - s_2^2)$$

* نفس القانون بس بـ s_1 و s_2

14.2) Principle of work and energy:

$$* U_{1-2} = \frac{1}{2}mv_2^2 - \frac{1}{2}mv_1^2 \quad , \quad \frac{1}{2}mv^2 = T_{\text{kinetic energy.}}$$

$$* U_{1-2} = T_2 - T_1$$

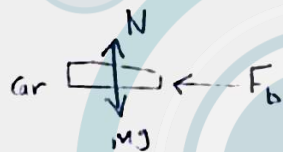
$$* T_1 + \sum U_{1-2} = T_2$$

11-2 prob

we will change the unit but the same solution.

$$F = [400 (10)^3 x^{1/2}] \text{ N}, \quad \text{mass} = 2 \text{ Mg}, \quad v_0 = 20 \text{ m/s}$$

slip $\Rightarrow T_2 = \text{Zero}, v_f = \text{Zero}$



$$T_1, \quad \sum U_{1-2} = T_2$$

$$T_1 + \sum U_{1-2} = \text{Zero}$$

$$\left(\frac{1}{2}\right)(2000)(20)^2 + \int_0^x 800 \cdot 10^3 x^{1/2} \cos 18^\circ dx = \text{Zero}$$

$$x = 0.825 \text{ m}$$

11-38 prob

$$\text{mass} = 60 \text{ kg}$$

$$v_1 = 5 \text{ m/s}$$

we need to find v_f , Normal force at point B

Sol:

$$T_1 + \sum U = T_2, \quad \text{we have only work of weight}$$

$$\left(\frac{1}{2}\right)(60)(5)^2 + mg \Delta y = \frac{1}{2} 60 (v_f)^2$$

$$\left(\frac{1}{2}\right)(60)(5)^2 + (60)(9.81)(10) = \left(\frac{1}{2}\right)(60) v_f^2$$

$$v_f = 14.87 \text{ m/s} \checkmark$$



$$+\uparrow \sum F \Rightarrow N - mg = m a_n$$

$$N - mg = m v^2 / \rho$$

$$N - (60)(9.81) = \frac{60 \cdot 14.87^2}{20}$$

$$N = 1250 \text{ N} \checkmark$$

$$\rho = \frac{\left(1 + \left(\frac{dy}{dx}\right)^2\right)^{3/2}}{d^2y/dx^2}, \quad \text{at } x=0 \text{ in point B}$$

$$\rho = 20 \text{ m}$$

L28/2

Prob 14-10

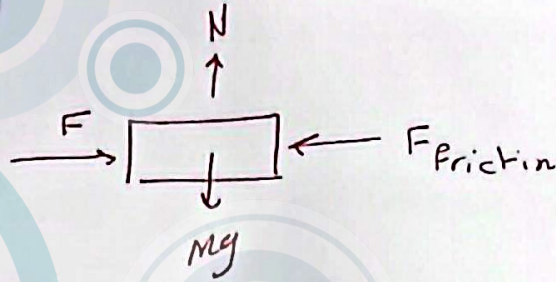
mass = 20 kg

finds,

$$v_f = 15$$

$$v_i = 6 \quad s = 0$$

$$\mu_k = 0.3$$



Solution:

$$F_{\text{fric}} = \mu_k N = 0.3 \times 196.2 = 58.86 \text{ N}$$

$$N - mg = 0 \quad N = 196.2 \text{ N} \quad \uparrow$$

$$T_1 + \sum U_{1-2} = T_2$$

$$\left(\frac{1}{2}\right)(20)(6)^2 + \int_0^s 50s^{1/2} ds - 58.86 \cdot s = \frac{1}{2}(20)(15)^2$$

$\cos 0 = 1$

$$s = 20.52 \text{ m} \quad \checkmark$$

Done ✓